

Model Selection Criterion for Multivariate Bounded Asymmetric Gaussian Mixture Model

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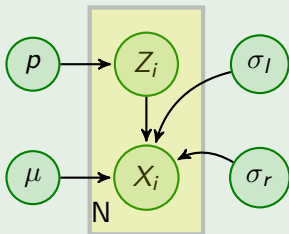
Outline

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Proposed Model

Mixture of Asymmetric Gaussian Distributions

Asymmetric Gaussian Mixture Model (AGMM)



Graphical representation of an asymmetric Gaussian mixture model

Mathematical Definition

$$p(\mathcal{X}, \mathcal{Z} | \Theta) = \prod_{i=1}^N \prod_{j=1}^K \left(p(\vec{X}_i | \xi_j) p_j \right)^{Z_{ij}} \quad (1)$$

- $p(\vec{X}_i | \xi_j)$ is the PDF of AGMM
- Asymmetric property
- **Unbounded support**

Mixture of Bounded Asymmetric Gaussian Distributions

Add bounded support

$$p(\vec{X}|\xi_j) = \frac{f(\vec{X}|\xi_j)H(\vec{X}|\Omega_j)}{\int_{\partial_j} f(\vec{u}|\xi_j)d\vec{u}}, \text{ where } H(\vec{X}|\Omega_j) = \begin{cases} 1 & \text{if } \vec{X} \in \partial_j \\ 0 & \text{otherwise} \end{cases} \quad (2)$$

Definition

$$f(\vec{X}|\xi_j) = \prod_{d=1}^D \frac{2}{\sqrt{2\pi}(\sigma_{l_{jd}} + \sigma_{r_{jd}})} \begin{cases} \exp\left[-\frac{(X_d - \mu_{jd})^2}{2\sigma_{l_{jd}}^2}\right] & \text{if } X_d < \mu_{jd} \\ \exp\left[-\frac{(X_d - \mu_{jd})^2}{2\sigma_{r_{jd}}^2}\right] & \text{if } X_d \geq \mu_{jd} \end{cases} \quad (3)$$

where $f(\vec{X}|\xi_j)$ is the PDF of AGMM

Minimum Message Length (MML)

$$\begin{aligned} \text{Mess Len}(K) \simeq & -\log(p(\Theta_K)) - \mathcal{L}(\Theta_K, Z, \mathcal{X}) + \frac{1}{2} \log |F(\Theta_K)| \\ & + \frac{N_p}{2} \left(1 + \log \left(\frac{1}{12} \right) \right) \end{aligned} \quad (4)$$

Θ_K set of parameters when mixture contains K components

$p(\Theta_K)$ prior probability

$\mathcal{L}(\Theta_K, Z, \mathcal{X})$ log-likelihood of mixture model

$|F(\Theta_K)|$ determinant of Fisher information matrix

N_p number of parameters (equal to $K(3D + 1)$)

Derivation of the prior $p(\Theta)$

$$p(\Theta) = p(\pi)p(\mu)p(\sigma_l)p(\sigma_r) \quad (5)$$

$$p(\pi) = \frac{\Gamma(\sum_{j=1}^K \eta_j)}{\sum_{j=1}^K \Gamma(\eta_j)} \sum_{j=1}^K p_j^{\eta_j - 1} \quad (6)$$

$$p(\mu_{jd}) = \frac{1}{\sigma_{ld} + \sigma_{rd}} \implies p(\vec{\mu}_j) = \prod_{d=1}^D \frac{1}{\sigma_{ld} + \sigma_{rd}} \quad (7)$$

$$p(\sigma_l) = \prod_{j=1}^K p(\vec{\sigma}_l_j), \quad p(\sigma_r) = \prod_{j=1}^K p(\vec{\sigma}_r_j) \quad (8)$$

Replacing parameters in Eq. (5) by Eqs. (6 & 7 & 8)

$$p(\Theta) = (M-1)! \prod_{d=1}^D \frac{1}{\sigma_{ld}^K \sigma_{rd}^K (\sigma_{ld} + \sigma_{rd})^K} \quad (9)$$

Derivation of the Fisher information matrix $|F(\Theta)|$

$$|F(\Theta)| = |F(\pi)||F(\mu)||F(\sigma_l)||F(\sigma_r)| \quad (10)$$

Approximate the Hessian matrix by complete-data Fisher information matrix

$$|F(\pi)| = \frac{N^{K-1}}{\sum_{j=1}^K p_j}, \quad F(\vec{\mu}_j)_{k_1, k_2} = \frac{\partial^2 \mathcal{L}(\Theta, Z, \mathcal{X}_j)}{\partial \mu_{jk_1} \partial \mu_{jk_2}} \quad (11)$$

$$F(\vec{\sigma}_{l_j})_{k_1, k_2} = \frac{\partial^2 \mathcal{L}(\Theta, Z, \mathcal{X}_j)}{\partial \sigma_{l_{jk_1}} \partial \sigma_{l_{jk_2}}}, \quad F(\vec{\sigma}_{r_j})_{k_1, k_2} = \frac{\partial^2 \mathcal{L}(\Theta, Z, \mathcal{X}_j)}{\partial \sigma_{r_{jk_1}} \partial \sigma_{r_{jk_2}}} \quad (12)$$

Model Learning Algorithm

Algorithm 1 Model Learning for BAGMM

```
1: Input: Dataset  $\mathcal{X} = \{\vec{X}_1, \dots, \vec{X}_N\}$ ,  $t_{min}$ ,  $K_{min}$ ,  $K_{max}$ .
2: Output:  $\Theta$ ,  $\mathcal{Z}$ ,  $K^*$ .
3: for  $K_{min} \leq K \leq K_{max}$  do
4:   {Initialization}:
5:    $K$ -Means (Compute  $\vec{\mu}_1, \dots, \vec{\mu}_K$  & cluster assignment)
6:   for all  $1 \leq j \leq K$  do
7:     Computation of  $p_j$  and  $\{(\vec{\sigma}_{l_j} \ \& \ \vec{\sigma}_{r_j}) = \vec{\sigma}_j\}$ 
8:   {Expectation Maximization}:
9:   while relative change in log-likelihood  $\geq t_{min}$  or iterations  $\leq epoch_{max}$  or relative
   changes of parameters  $\geq t_{min}$  do
10:    {[E Step]}:
11:    for all  $1 \leq j \leq K$  do
12:      Compute  $p(j|\vec{X}_i)$  for  $i = 1, \dots, N$ .
13:    {[M step]}:
14:    update bounded support range
15:    for all  $1 \leq j \leq K$  do
16:      Estimate  $p_j$ ,  $\vec{\mu}_j$ ,  $\vec{\sigma}_{l_j}$  &  $\vec{\sigma}_{r_j}$ 
17:    end while
18:    Compute  $K^* = \arg \min MML(K)$ 
19: end for
```


Execution Information

Table: Execution information of MML on synthetic dataset

Execution information on synthetic dataset(seconds)				
Mixture Models	Clusters	Time	Accuracy	Iterations
BAGMM	2 clusters	2.35	71.3%	5
BAGMM	3 clusters	8.60	85.7%	2
BAGMM	4 clusters	12.09	72.2%	4
BAGMM	5 clusters	12.58	65.7%	5

All experiments are running on a Macbook Pro 2015 with Dual-Core Intel Core i5 CPU. The BAGMM is as relatively fast as the AGMM for 5 clusters or more, but in the case of less than 5 clusters, the AGMM is a little bit faster. The BAGMM always converges faster than the AGMM with less iterations.

Conclusion

- Proposed model selection criterion for bounded support asymmetric Gaussian mixture model (BAGMM) using minimum message length (MML)
- Validated using synthetic data, real data and occupancy detection application
- Compared with asymmetric Gaussian mixture model (AGMM)

For Further Reading I



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